GPS Concepts

- 1. Elasped time distance equals rate times interval of time.
 - Procedure is called pseudorange C/A code measurement.
 - Satellite transmits code having particular pattern.
 - Receiver generates same pattern and compares to signal from satellite.
 Difference (shift) is measure of transit time for signal from satellite to receiver (passive).
 - Distance from satellite to antenna is the measured time interval times the speed of light.
 - Antenna position is 3-dimensional distance/distance/distance intersection. Three satellites are needed to find three unknowns (lat/long/height).
 - Due to imprecise clock, distances are not quite correct. With 4th satellite, local clock correction is found as part of the solution.
 - Subject to satellite geometry (PDOP), "accurate" local position is found.
- 2. Doppler shift change in observed frequency due to movement.
 - Transit satellite system. Used for navigation 1964 to 199?.
 - Satellite broadcasts very stable frequency.
 - Frequency received is:
 - shorter if range is decreasing.
 - longer if range is increasing.
 - instantaneously identical for closest approach (time).
 - If the two frequencies are subtracted, the result is an intermediate frequency called the "beat" frequency and used to compute position.
 - Many satellite passes required to determine "accurate" position.

3. Interferometry

- Based upon interference of waves (light/radio)
- Very Long Baseline Interferometry (VLBI) & use of quasars
- Measure position on wave within 1% development continues
- L1 frequency wavelength is 19 cm, ultimate resolution 2 mm
- Question for surveyors is which wavelength integer ambiguity
- Many techniques developed to find "the right integer" etc.
 - Knowing approximate location helps
 - Doppler data can help narrow the search
 - Count cycles while "locked" onto satellites
 - Differencing combinations between satellites & receivers
 - Dual frequency receivers help resolve atmospheric effects
 - Use many satellites and "best" geometry